

Introduction to Formal Methods

Lecture 3 Bounded Model Checking Hossein Hojjat & Fatemeh Ghassemi

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- Idea: only look for bugs up to specific depth
- One of the most successful techniques for hardware analysis
- Enabled by advances in SAT solving
- Mostly incomplete in practice
 - Can find bugs, cannot prove a system satisfies a specification

- Represent the system and the specification symbolically
 - By using e.g. propositional logic formulas $(p, \overline{p}, p \lor q, p \land q, p \rightarrow q,...)$
- Reduce the bounded reachability problem to satisfiability of a Boolean formula
- Use efficient theorem provers (SAT solvers) for solving the satisfiability problem

Key idea:

Instead of reasoning about individual states, reason about sets of states

How do we represent a set of states?

Symbolic Representation:

• Set = predicate

Predicate P(x) represents set S: $S = \{x \mid P(x)\}$

• Set of states = predicate on state variables

Examples:

• Assume 3 state variables, p, q, r of type Boolean.

 $S_1: \qquad p \lor q = \{ p\overline{q}r, p\overline{q}\overline{r}, \overline{p}qr, \overline{p}q\overline{r}, pqr, pq\overline{r} \}$

• Assume 3 state variables, $x,\,i,\,b,$ of types Real, Integer, Boolean. $S_2:\qquad (x\leq 0)\wedge (b\to i\geq 0)$

How many states are in S_2 ?

Key idea:

Use a predicate on two copies of the state variables:

unprimed (current state) + primed (next state)

- If \vec{x} is the vector of state variables, then the transition relation R is a predicate on \vec{x} and $\vec{x'}$

 $R(\vec{x}, \vec{x'})$

• e.g., for three state variables, x, i, b:

R(x, i, b, x', i', b')

Examples:

• Assume one state variable, p, of type Boolean

$$R_1: (p \to \overline{p'}) \land (\overline{p} \to p')$$

Which transition relation does this represent? Is it a relation or a function (deterministic)?

• Assume one state variable, n, of type Integer.

$$R_2: \qquad n'=n+1 \lor n'=n$$

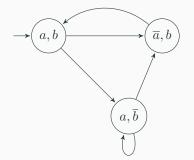
Which transition relation does this represent? Is it a relation or a function (deterministic)?

(V, I, R)

where

- $V = \{x_1, x_2, \cdots, x_n\}$: finite set of (Boolean) state variables
- Predicate $I(\vec{x})$ on vector $\vec{x} = (x_1, \cdots, x_n)$ represents the set S_0 of initial states
- Predicate $R(\vec{x},\vec{x'})$ represents the transition relation R

Represent the transition system symbolically $V = \{a, b\}$



Question: Can a "bad" state be reached in up to n transitions? Given a transition system (V, I, R) and a set of bad states P, does there exist a path

$$s_0 \longrightarrow s_1 \longrightarrow \cdots \longrightarrow s_k$$

in the transition system such that $s_0 \in I$ and $s_k \in P$, and $k \leq n$

Key idea: Reduce the above question to a SAT (satisfiability) problem.

Transition system (V, I, R) and a set of bad states P

• Bad state reachable in 0 steps iff

 $SAT(I(\vec{x}) \wedge P(\vec{x}))$

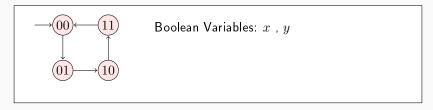
• Bad state reachable in 1 step iff

$$SAT(I(\vec{x_0}) \land R(\vec{x_0}, \vec{x_1}) \land P(\vec{x_1}))$$

- ...
- Bad state reachable in n steps iff

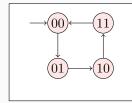
$$SAT(I(\vec{x_0}) \land R(\vec{x_0}, \vec{x_1}) \land \dots \land R(\vec{x_{n-1}}, \vec{x_n}) \land P(\vec{x_n}))$$

Is the state $(x \wedge y)$ reachable from the initial state?



• Represent initial states and the transition relation as Boolean formulas

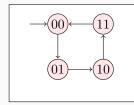
Is the state $(x \wedge y)$ reachable from the initial state?



Boolean Variables: x , y Initial State: $I(x,y) = \overline{x} \wedge \overline{y}$

• Represent initial states and the transition relation as Boolean formulas

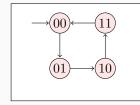
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Boolean Variables: x, yInitial State: $I(x,y) = \overline{x} \wedge \overline{y}$ Transition Relation: $R(x,y,x',y') = (x' = (x \neq y) \wedge y' = \overline{y})$

• Represent initial states and the transition relation as Boolean formulas

Is the state $(x \wedge y)$ reachable from the initial state?



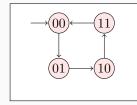
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- Represent initial states and the transition relation as Boolean formulas
- Unroll the transition relation up to a bound k starting from the initial states

$$(\overline{x_0} \land \overline{y_0}) \land \qquad \begin{pmatrix} x_1 = (x_0 \neq y_0) \land y_1 = \overline{y_0} \\ \land \\ x_2 = (x_1 \neq y_1) \land y_2 = \overline{y_1} \\ \land \\ x_3 = (x_2 \neq y_2) \land y_3 = \overline{y_2} \end{pmatrix} \land \qquad \begin{pmatrix} \lor \\ (x_1 \land y_1) \\ \lor \\ (x_2 \land y_2) \\ \lor \\ (x_3 \land y_3) \end{pmatrix}$$

 $(x_0 \wedge y_0)$

Is the state $(x \wedge y)$ reachable from the initial state?



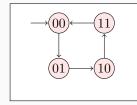
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 $(x_0 \wedge y_0)$

Is the state $(x \wedge y)$ reachable from the initial state?



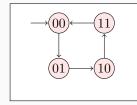
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 $(x_0 \wedge y_0)$

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Boolean Variables: x, yInitial State: $I(x, y) = \overline{x} \wedge \overline{y}$ Transition Relation: $R(x, y, x', y') = (x' = (x \neq y) \wedge y' = \overline{y})$

 $\left((x_0 \wedge y_0) \right)$

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- Represent initial states and the transition relation as Boolean formulas
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$$(\overline{x_0} \land \overline{y_0}) \land \qquad \begin{pmatrix} x_1 = (x_0 \neq y_0) \land y_1 = \overline{y_0} \\ \land \\ x_2 = (x_1 \neq y_1) \land y_2 = \overline{y_1} \\ \land \\ x_3 = (x_2 \neq y_2) \land y_3 = \overline{y_2} \end{pmatrix} \land \qquad \begin{pmatrix} \lor & \lor & \lor \\ (x_1 \land y_1) \\ \lor \\ (x_2 \land y_2) \\ \lor \\ (x_3 \land y_3) \end{pmatrix}$$

Completeness

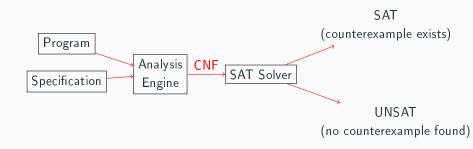
- Typical application of Bounded Model Checking: increment depth until counter-example found
- Incomplete BMC good for falsification not verification
- Can be used for verification by choosing depth which is large enough
- For every **finite** system and a property, there exists a number such that the absence of errors up to that number proves correctness
- Diameter d = longest shortest path from an initial state to any other reachable state



- d = 2
- Using diameter bound is often not practical
- Worst case diameter is exponential. Obtaining better bounds is sometimes possible, but generally intractable

Main Idea:

Given a program and a specification use a SAT-solver to find whether there exists an execution that violates the specification



- Bounded model checker by University of Oxford http://www.cprover.org/cbmc/
- Processes C code and subset of C++
- Simple Safety Claims
 - Array bound checks (i.e., buffer overflow)
 - Division by zero
 - Pointer checks (i.e., NULL pointer dereference)
 - Arithmetic overflow
 - User supplied assertions (i.e., assert (i > j))
 - etc

Transform a programs into a set of equations

- 1. Simplify control flow
- 2. Unwind all of the loops
- 3. Convert into Single Static Assignment (SSA)
- 4. Convert into equations
- 5. Bit-blast
- 6. Solve with a SAT Solver
- 7. Convert SAT assignment into a counterexample

- All side effect are removed
 - e.g., j=i++ becomes j=i;i=i+1
- Control Flow is made explicit
 - continue, break replaced by goto
- All loops are simplified into one form
 - for, do while replaced by while

- All loops are unwound
 - can use different unwinding bounds for different loops
 - to check whether unwinding is sufficient special "unwinding assertion" claims are added
- If a program satisfies all of its claims and all unwinding assertions then it is correct!
- Same for backward goto jumps and recursive functions

```
void f(...) {
    ...
    while(cond) {
        Body;
    }
    Remainder;
}
```

- while loops are unwound iteratively
- break / continue replaced by goto

```
void f(...) {
    ...
    if(cond) {
        Body;
        while(cond) {
            Body;
            }
        }
        Remainder;
}
```

- while loops are unwound iteratively
- break / continue replaced by goto

```
void f(...) {
  . . .
  if(cond) {
    Body;
     if(cond) {
        Body;
        while(cond) {
           Body;
        }
     }
  }
  Remainder;
}
```

- while loops are unwound iteratively
- break / continue replaced by goto

```
void f(...) {
   . . .
  if(cond) {
    Body;
     if(cond) {
        Body;
        assert(!cond)
     }
  }
  Remainder;
```

}

- while loops are unwound iteratively
- break / continue replaced by goto
- Assertion inserted after last iteration: violated if program runs longer than bound permits

Example: Sufficient Loop Unwinding

}

```
void f(...) {
                           j = 1
                           if(j <= 2) {
                             j = j + 1;
void f(...) {
                             if(j <= 2) {
  j = 1
                               j = j + 1;
  while (j <= 2)
                                if(j <= 2) {
    j = j + 1;
                                  j = j + 1;
                                  assert(!(j <= 2));</pre>
  Remainder;
                                }
                             }
                           }
                           Remainder;
                         }
```

Example: Insufficient Loop Unwinding

```
void f(...) {
                           j = 1
                           if(j <= 10) {
                             j = j + 1;
void f(...) {
                              if(j <= 10) {
  j = 1
                               j = j + 1;
  while (j <= 10)
                                if(j <= 10) {
    j = j + 1;
                                  j = j + 1;
                                  assert(!(j <= 10));</pre>
  Remainder;
}
                                }
                             }
                           }
                           Remainder;
                         }
```

Easy to transform when every variable is only assigned once!



When a variable is assigned multiple times, use a new variable for the RHS of each assignment

- Machine arithmetic: Bounded integer e.g., 8bit, 32bit, 64bit
- Numbers are represented by vector of Boolean variables $\langle b_{n-1}, b_{n-2}, ..., b_0 \rangle$
- Encoding of overflow/rounding-behaviour derived from hardware implementation

• E. Clarke, A. Biere, R. Raimi, and Y. Zhu. "Bounded model checking using satisfiability solving", Formal Methods in System Design, 19(1):7-34, 2001